

Code Completion with Neural Attention and Pointer Networks

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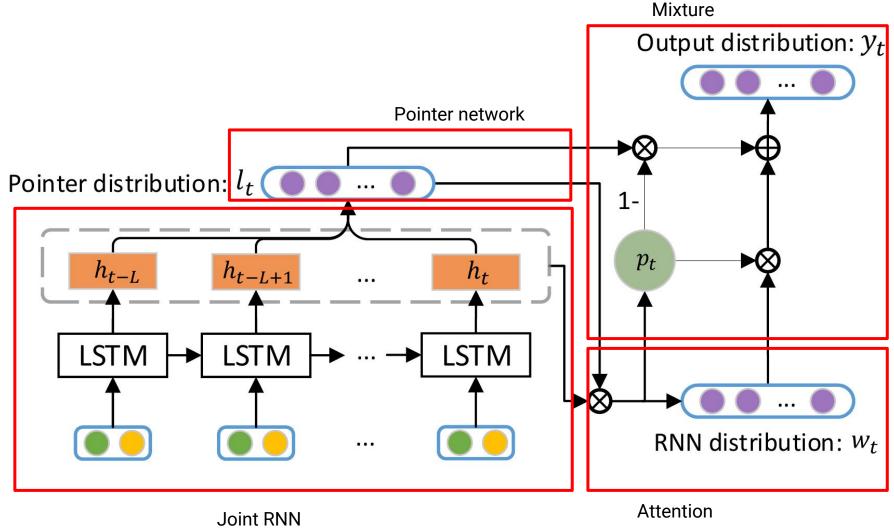
Presented by Ondrej Skopek

Goal: Predict out-of-vocabulary words using local context

Add

(illustrative image)

Pointer mixture networks



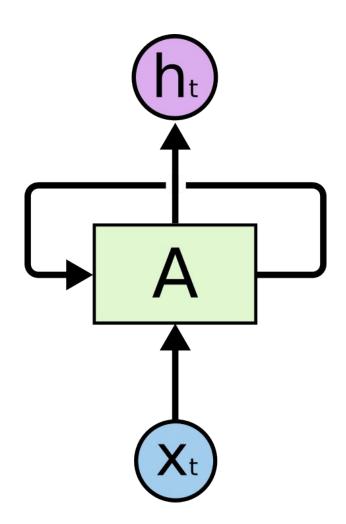
Outline

- Recurrent neural networks
- Attention
- Pointer networks

- Data representation
- Pointer mixture network

- Experimental evaluation
- Summary

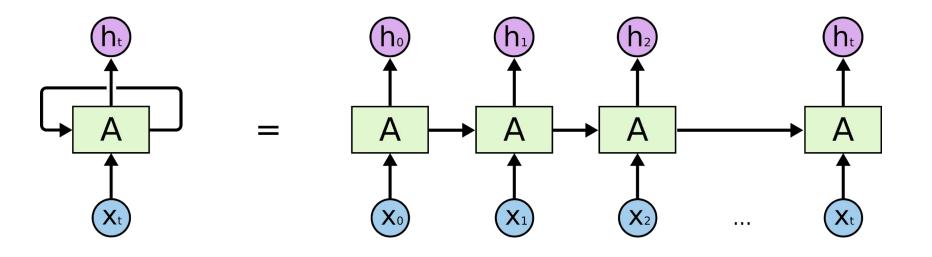
Recurrent neural networks

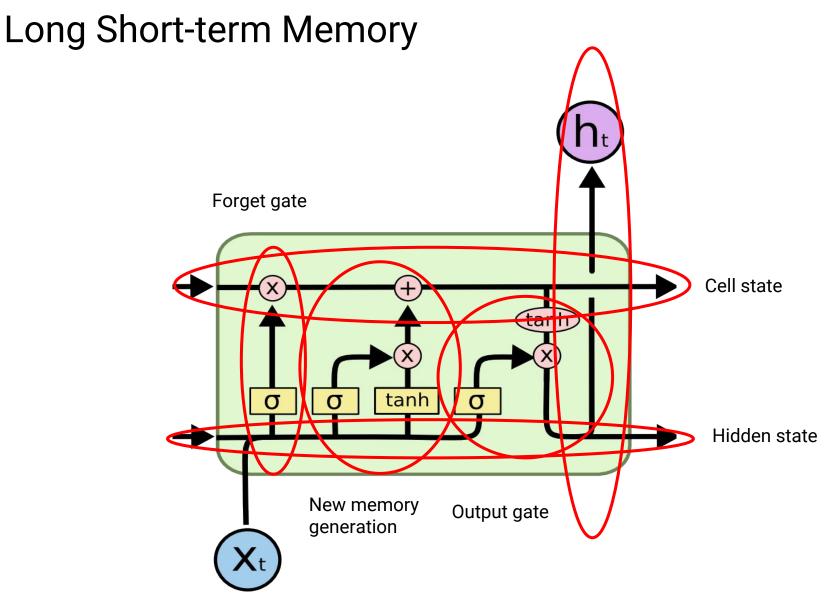


 $h_t = A(h_{t-1}, x_t)$

Credits: Olah, C. Understanding LSTM Networks. colah's blog (2015).

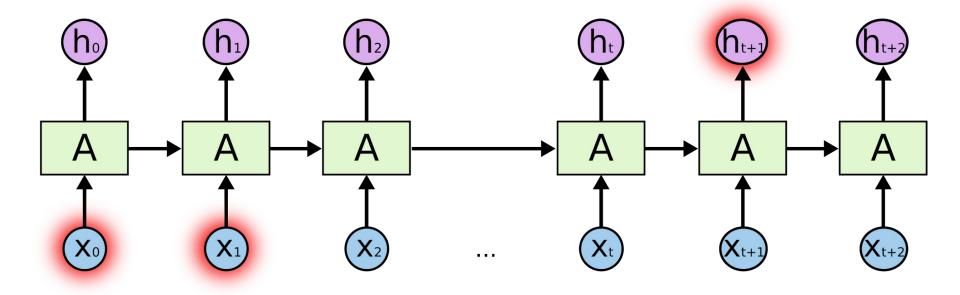
Recurrent neural networks – unrolling





Credits: Hochreiter, S. & Schmidhuber, J. Long Short-term Memory. Neural Computation 9, 1735–1780 (1997). Olah, C. Understanding LSTM Networks. colah's blog (2015).

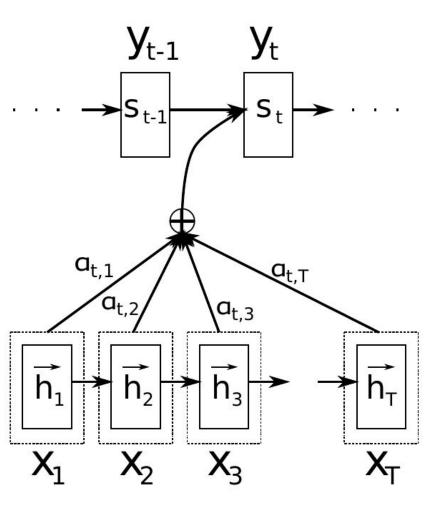
Recurrent neural networks – long-term dependencies



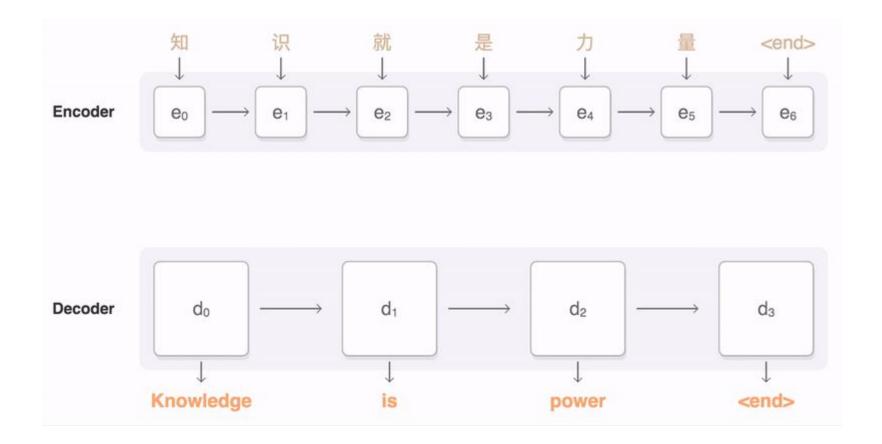
Attention

- Choose which context to look at when predicting
- Overcome the hidden state bottleneck

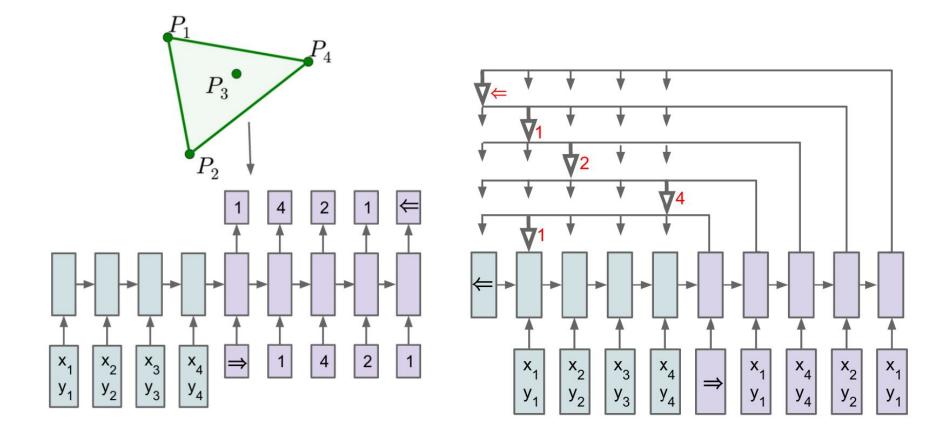
$$egin{aligned} &A^i_j = v^T anh(W_h h_j + W_s s_i)\ &lpha^i = ext{softmax}(A^i)\ &c_i = \sum_{j=1}^n lpha^i_j h_j \end{aligned}$$



Attention (cont.)



Pointer networks



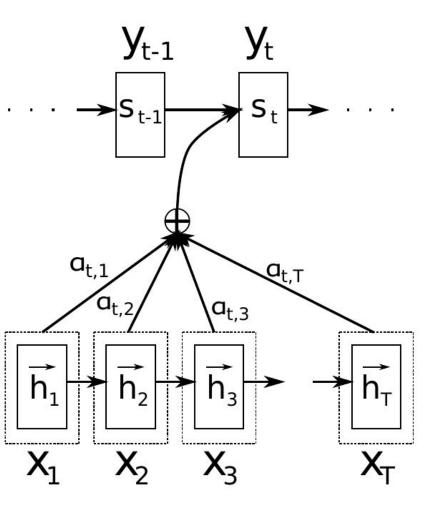
(a) Sequence-to-Sequence

(b) Ptr-Net

Pointer networks (cont.)

- Based on Attention
- Softmax over a dictionary of inputs
- Output models a conditional distribution of the next output token

$$egin{aligned} &A_j^i = v^T anh(W_h h_j + W_s s_i) \ &p(C_i | C_1, \dots, C_{i-1}, \mathcal{P}) = ext{softmax}(A^i) \end{aligned}$$



Credits: Vinyals, O., Fortunato, M. & Jaitly, N. Pointer Networks. (2015). Bahdanau, D., Cho, K. & Bengio, Y. Neural Machine Translation by Jointly Learning to Align and Translate. (2014).

Outline

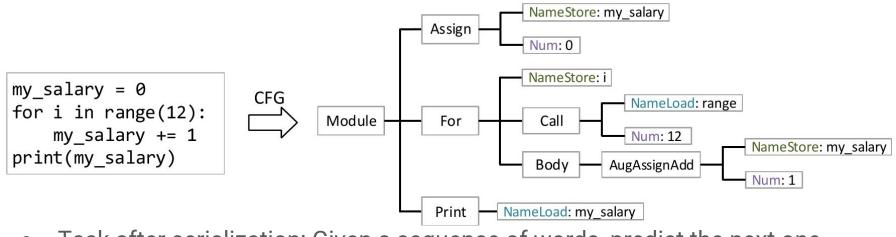
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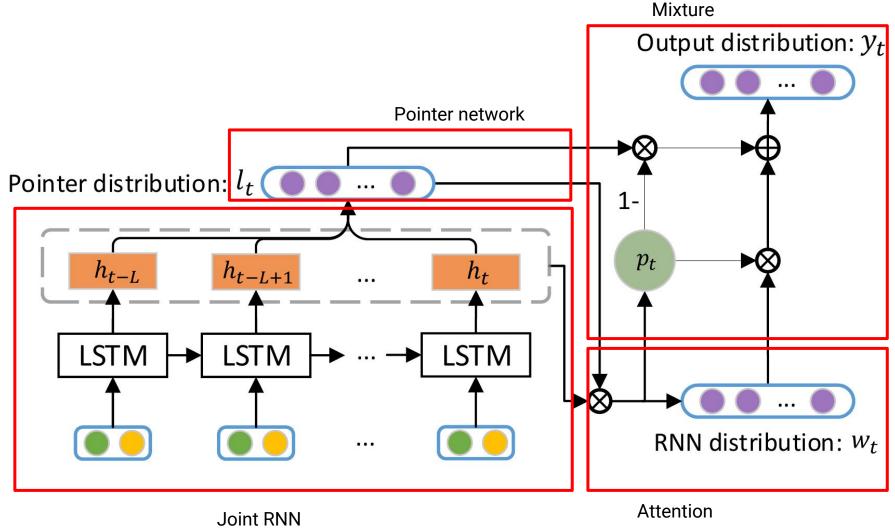
Data representation

- Corpus of Abstract Syntax Trees (ASTs)
 - Parsed using a context-free grammar
- Each node has a type and a value (type:value)
 - Non-leaf value: EMPTY, unknown value: UNK, end of program: EOF
- Task: Code completion



Task after serialization: Given a sequence of words, predict the next one

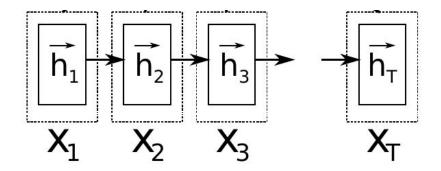
Pointer mixture networks



RNN with adapted Attention

- Intermediate goal
 - Produce two distributions at time t

 $w_t \in \mathbb{R}^V \ l_t \in \mathbb{R}^L$



- RNN with Attention (fixed unrolling)
 - \circ L input window size (L = 50)
 - V vocabulary size (differs)
 - \circ k size of hidden state (k = 1500)

 $egin{aligned} M_t &= [h_{t-L}, \dots, h_{t-1}] \in \mathbb{R}^{k imes L} \ A_t &= v^T ext{tanh}ig(W_m M_t + (W_h h_t) 1_L^Tig) \ lpha_t &= ext{softmax}(A_t) \ c_t &= M_t lpha_t^T \end{aligned}$

Credits: Vinyals, O., Fortunato, M. & Jaitly, N. Pointer Networks. (2015).

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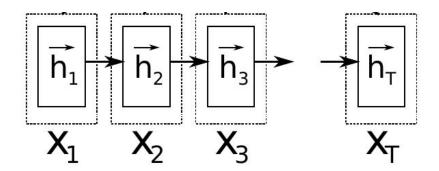
Attention & Pointer components

- Attention for the "decoder"
 - Condition on both the hidden state and context vector

- Pointer network
 - Reuses Attention outputs

 $egin{aligned} G_t &= anh(W_g[h_t;c_t]) \ w_t &= ext{softmax}(W_vG_t+b_v) \ ext{where} \ W_g \in \mathbb{R}^{k imes 2k}, W_v \in \mathbb{R}^{V imes k} \end{aligned}$





Credits: Vinyals, O., Fortunato, M. & Jaitly, N. Pointer Networks. (2015). Bahdanau, D., Cho, K. & Bengio, Y. Neural Machine Translation by Jointly Learning to Align and Translate. (2014).

Mixture component

• Combine the two distributions into one

$$w_t \in \mathbb{R}^V \ l_t \in \mathbb{R}^L$$

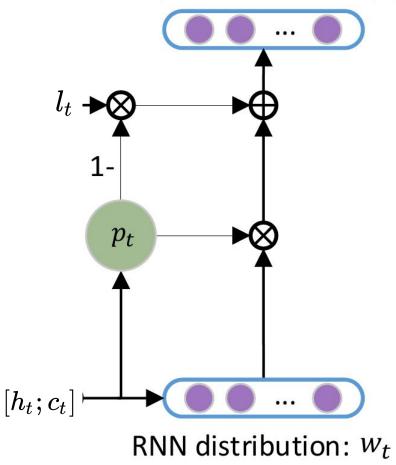
• Using

$$egin{aligned} p_t &= \sigma(W_p[h_t;c_t]+b_p) \ y_t &= [p_t w_t;(1-p_t)l_t] \end{aligned}$$

where

$$W_p \in \mathbb{R}^{2k imes 1}, \ b_p \in \mathbb{R}$$

Output distribution: y_t



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Experimental evaluation

Data

- JavaScript and Python datasets
 - <u>http://plml.ethz.ch</u>
- Each program divided into segments of 50 consecutive tokens
 - Last segment padded with EOF
- AST data as described beforehand
 - Type embedding (300 dimensions)
 - Value embedding (1200 dimensions)
- No unknown word problem for types!

Table 1: Dataset Statistics				
	JS	PY		
Training Queries	$10.7 * 10^7$	$6.2 * 10^7$		
Test Queries	$5.3 * 10^{7}$	$3.0 * 10^{7}$		
Type Vocabulary	95	329		
Value Vocabulary	$2.6 * 10^{6}$	$3.4 * 10^{6}$		

Model & training parameters

- Single-layer LSTM, unrolling length 50
- Hidden unit size 1500
- Forget gate biases initialized to 1
- Cross-entropy loss function
- Adam optimizer (learning rate 0.001 + decay)
- Gradient clipping (L2 norm [0, 5])
- Batch size 128
- 8 epochs
- Trainiable initial states
 - Initialized to 0
 - All other parameters ~ Unif([-0.05, 0.05])

Experimental evaluation (cont.)

Training conditions

- Hidden state reset to trainable initial state only if segment from a different program, otherwise last hidden state reused
- If label UNK, set loss to 0 during training
- During training and test, UNK prediction considered incorrect

Labels

- Vocabulary: K most frequent words
- If in vocabulary: word ID
- If in attention window: label it as the last attention position
 - If not, labeled as UNK

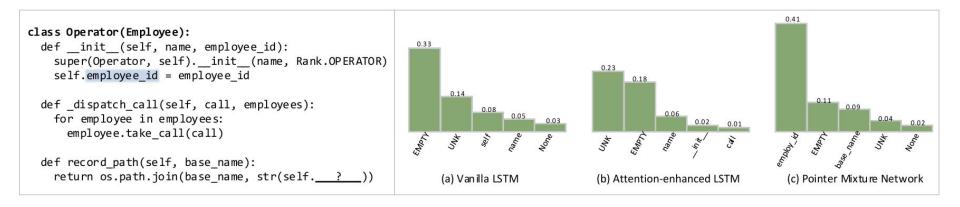
	JS			PY		
Vocabulary Size (OoV Rate)	1k (20%)	10k (11%)	50k (7%)	1k (24%)	10k (16%)	50k (11%)
Vanilla LSTM	69.9%	75.8%	78.6%	63.6%	66.3%	67.3%
Attention-enhanced LSTM (ours)	71.7%	78.1%	80.6%	64.9%	68.4%	69.8%
Pointer Mixture Network (ours)	73.2%	78.9%	81.0%	66.4%	68.9%	70.1%

Comparison to other results

	JS		PY	
	TYPE	VALUE	TYPE	VALUE
Vanilla LSTM	87.1%	78.6%	79.3%	67.3%
Attention-enhanced LSTM (ours)	88.6%	80.6%	80.6%	69.8%
Pointer Mixture Network (ours)	-	81.0%		70.1%
LSTM (Liu et al. 2016)	84.8%	76.6%		
Probabilistic Model (Raychev et al. 2016)	84.8% 83.9%	76.6% 82.9%	- 76.3%	- 69.2%

	JS_1k	PY_1k
Pointer Random Network	71.4%	64.8%
Attention-enhanced LSTM	71.7%	64.9%
Pointer Mixture Network	73.2%	66.4 %

Example result



Summary

- Applied neural language models to code completion
- Demonstrated the effectiveness of the Attention mechanism
- Proposed a Pointer Mixture Network to deal with the out-of-vocabulary values

Future work

- Encode more static type information
- Combine the two distributions in a different way
- Use both backward and forward context to predict the given node
- Attempt to learn longer dependencies for out-of-vocabulary values (L>50)



Thank you for your attention!